

# An Explicit Superconvergent Weak Galerkin Finite Element Method for the Heat Equation

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**Abstract.** An explicit two-order superconvergent weak Galerkin finite element method is designed and analyzed for the heat equation on triangular and tetrahedral grids. For two-order superconvergent  $P_k$  weak Galerkin finite elements, the auxiliary inter-element functions must be  $P_{k+1}$  polynomials. In order to achieve the superconvergence, the usual  $H^1$ -stabilizer must be also eliminated. For time-explicit weak Galerkin method, a time-stabilizer is added, on which the time-derivative of the auxiliary variables can be defined. But for the two-order superconvergent weak Galerkin finite elements, the time-stabilizer must be very weak, an  $H^{-2}$ -like inner-product instead of an  $L^2$ -like inner-product. We show the two-order superconvergence for both semi-discrete and fully-discrete schemes. Numerical examples are provided.

**AMS subject classifications:** 65N15, 65N30

**Key words:** Parabolic equations, finite element, weak Galerkin method, polytopal mesh.

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## 1 Introduction

The weak Galerkin (WG) finite element method [32] solves numerically partial differential equations with discontinuous polynomials on polytopal meshes. The method has been developed for many partial differential equations, cf. [2–4, 9, 11–16, 18–21, 24, 25, 27–30, 32, 34, 35, 39, 41, 43, 44, 47, 50–52].

In the  $P_k$  weak Galerkin (WG) finite element method, auxiliary variables of  $P_{k-1}$ , or  $P_k$ , or  $P_{k+1}$  polynomials are introduced on the inter-element edges or face-polygons. The continuity of these discontinuous polynomials are enforced weakly by an  $H^1$ -stabilizer. However, for the two-order superconvergent WG finite element method in this manuscript, the auxiliary variables must be of  $P_{k+1}$  polynomials on triangular or tetrahedral meshes. Also the  $H^1$ -stabilizer must be eliminated from the weak formulation. The

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weak continuity on the discontinuous polynomials is achieved by the weak gradient of properly chosen high-degree polynomials, cf. [36–38, 40, 42, 45, 46].

For time-dependent problems, for a long time, only the implicit WG finite element methods can be applied, cf. [1, 5–8, 10, 17, 22, 26, 48, 49, 53–56]. This is because the time direction updates of the auxiliary variables are not possible. Recently, [33] designs an explicit WG finite element method for the parabolic problems where an  $L^2$ -stabilizer is added to the weak formulation. The time derivative is applied inside this  $L^2$ -stabilizer so that time-direction updates of the auxiliary variables are consistent.

In this work, we extend the explicit WG finite element method of [33] to the two-order superconvergent WG finite element method, on triangular or tetrahedral meshes. In order to obtain the two-order superconvergence, the  $L^2$ -like time-stabilizer in [33] is replaced by a very weak  $H^{-2}(\Omega)$ -like stabilizer. Of course, the underlying WG finite element space must be a two-order superconvergent one, i.e., in this paper, the  $P_k$ - $P_{k+1}$ - $P_{k+1}^d$  WG finite element on triangular or tetrahedral meshes, where the first  $P_k$  stands for the polynomial space inside each element, the second  $P_{k+1}$  stands for the polynomial space on each edge/triangle between two elements, and the third  $P_{k+1}^d$  stands for the discrete space of the weak gradient on each element. Both semi-discrete and fully-discrete numerical schemes are analyzed. Two-order above the optimal-order error estimates are established for both schemes in  $H^1$ -norm. Numerical experiments are presented, confirming the theory.

## 2 Semi-discrete scheme

### 2.1 The WG finite element space

Let  $\mathcal{T}_h$  be a quasi-uniform triangular or tetrahedral mesh of the domain  $\Omega$ . Denote by  $\mathcal{E}_h$  the set of all edges or triangles in  $\mathcal{T}_h$  and  $\mathcal{E}_h^0 = \mathcal{E}_h \setminus \partial\Omega$  the set of all interior edges or triangles. For each element  $T \in \mathcal{T}_h$ , denote by  $h_T$  its diameter and  $h = \max_{T \in \mathcal{T}_h} h_T$  the mesh size of  $\mathcal{T}_h$ . Denote by  $P_k(T)$  the space of polynomials of degree less than or equal to  $k$  on  $T$ . We denote the piecewise bilinear forms in short notations,

$$\begin{aligned} (u_0, v_0)_{\mathcal{T}_h} &= \sum_{T \in \mathcal{T}_h} (u_0, v_0)_T, \\ \langle u_b, v_b \rangle_{\partial\mathcal{T}_h} &= \sum_{T \in \mathcal{T}_h} \sum_{e \in \partial T} \langle u_b, v_b \rangle_e. \end{aligned}$$

The  $P_k$  WG finite element space  $V_h$  on the mesh  $\mathcal{T}_h$  is defined as follows,  $k \geq 1$ ,

$$V_h = \{v = \{v_0, v_b\} : v_0|_T \in P_k(T), v_b|_e \in P_{k+1}(e), e \subset \partial T, \forall T \in \mathcal{T}_h\}. \quad (2.1)$$

We note that a function  $v \in V_h$  has a single value auxiliary  $v_b$  on the two sides of  $e \in \mathcal{E}_h$ . The subspace of  $V_h$  consisting of functions with vanishing  $v_b$  on  $e \subset \partial\Omega$  is denoted as  $V_h^0$ .