

A Review on Two Types of Sonic Interfaces

Myoungjean Bae*

*Department of Mathematical Sciences, KAIST, 291 Daehak-ro,
Yuseong-gu, Daejeon, 43141, Korea.*

Received 9 May 2024; Accepted 23 June 2024

Abstract. In this paper, two examples of sonic interfaces ([2–6]) are presented. The first example shows the case of sonic interfaces as weak discontinuities in self-similar shock configurations of unsteady Euler system. The second example shows the case of sonic interfaces as regular interfaces in accelerating transonic flows governed by the steady Euler-Poisson system with self-generated electric forces. And, we discuss analytic differences of the two examples, and introduce an open problem on decelerating transonic solution to the steady Euler-Poisson system.

AMS subject classifications: 35C06, 35M10, 35M30, 35Q31, 76H05, 76N10

Key words: Keldysh type, transonic, sonic interface, weak discontinuity, regular interface.

1 A sonic interface as a weak discontinuity

Fix a constant $\varepsilon_0 > 0$. Given a function $f : [0, \varepsilon_0] \rightarrow \mathbb{R}_+$ with

$$\begin{aligned} \|f\|_{C^{1,1}([0, \varepsilon_0])} &< \infty, \quad f(0) > 0, \\ \frac{df}{dx} &\geq \omega > 0, \quad \forall 0 \leq x \leq \varepsilon_0, \end{aligned} \tag{1.1}$$

set

$$P_0 := (0, f(0)),$$

*Corresponding author. *Email address:* mjbae@kaist.ac.kr (M. Bae)

and define the domain

$$\mathcal{Q}_{\varepsilon_0}^f := \{(x, y) : 0 < x < \varepsilon_0, 0 < y < f(x)\}. \quad (1.2)$$

For each $t \in (0, f(0))$, set

$$\mathcal{R}_t := \left(0, \frac{\varepsilon_0}{2}\right) \times (0, f(0) - t).$$

Given two constants $a > 0$ and $b > 0$, and functions $\beta_k \in C(\partial \mathcal{Q}_{\varepsilon_0}^f \cap \{y = f(x)\})$ for $k = 1, 2, 3$, consider the equation

$$(2x - a\psi_x + O_1)\psi_{xx} + O_2\psi_{xy} + (b + O_3)\psi_{yy} - (1 + O_4)\psi_x + O_5\psi_y = 0 \quad \text{in } \mathcal{Q}_{\varepsilon_0}^f, \quad (1.3)$$

and the boundary conditions

$$\psi = 0 \quad \text{on } \partial \mathcal{Q}_{\varepsilon_0}^f \cap \{x = 0\}, \quad (1.4)$$

$$\partial_y \psi = 0 \quad \text{on } \partial \mathcal{Q}_{\varepsilon_0}^f \cap \{y = 0\}, \quad (1.5)$$

$$\beta_1(x, y)\psi_x + \beta_2(x, y)\psi_y + \beta_3(x, y)\psi = 0 \quad \text{on } \partial \mathcal{Q}_{\varepsilon_0}^f \cap \{y = f(x)\}. \quad (1.6)$$

In addition, assume that

$$\beta_1(x, y) \geq \lambda, \quad |\beta_2(x, y), \beta_3(x, y)| \leq \frac{1}{\lambda} \quad \text{on } \partial \mathcal{Q}_{\varepsilon_0}^f \cap \{y = f(x)\} \quad (1.7)$$

for some constant $\lambda > 0$.

Theorem 1.1 ([1, Theorems 3.1, 4.2]). Suppose that a function $\psi: \overline{\mathcal{Q}_{\varepsilon_0}^f} \rightarrow \mathbb{R}$ satisfies the following conditions:

$$(i) \quad \psi \in C^2(\mathcal{Q}_{\varepsilon_0}^f) \cap C^{1,1}(\overline{\mathcal{Q}_{\varepsilon_0}^f}),$$

$$(ii) \quad \psi > 0 \text{ in } \mathcal{Q}_{\varepsilon_0}^f,$$

(iii) there exist constants $\mu > 0$ and $\delta \in (0, 1)$ such that

$$-\mu \leq \frac{\psi_x(x, y)}{x} \leq \frac{2 - \delta}{a} \quad \text{in } \mathcal{Q}_{\varepsilon_0}^f,$$

(iv) ψ satisfies (1.3)-(1.6).