Approximation Results for Gradient Flow Trained Neural Networks

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Abstract. The paper contains approximation guarantees for neural networks that are trained with gradient flow, with error measured in the continuous $L_2(\mathbb{S}^{d-1})$ -norm on the d-dimensional unit sphere and targets that are Sobolev smooth. The networks are fully connected of constant depth and increasing width. We show gradient flow convergence based on a neural tangent kernel (NTK) argument for the non-convex optimization of the second but last layer. Unlike standard NTK analysis, the continuous error norm implies an underparametrized regime, possible by the natural smoothness assumption required for approximation. The typical over-parametrization re-enters the results in form of a loss in approximation rate relative to established approximation methods for Sobolev smooth functions.

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Contents

1	Introduction	108
2	Main result 2.1 Notations	112 114
3	Coercivity of the NTK	118
4	Numerical experiments	120
5	Proof overview 5.1 Preliminaries	121 123 124 124

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	5.4	Assumption (5.9): Concentration	127
	5.5	Assumption (5.7): Weights stay close to initial	
6	Proc	of of the main result	128
	6.1	Proof of Lemma 5.2: Generalized convergence	128
	6.2	Proof of Lemma 5.3: NTK Hölder continuity	
	6.3		
		6.3.1 Concentration of the last layer	
		6.3.2 Perturbation of covariances	
		6.3.3 Concentration of the NTK	
	6.4		
	6.5	• .	
7	Tecl	nnical supplements	156
	7.1	Hölder spaces	156
	7.2	Concentration	162
	7.3	Hermite polynomials	
	7.4	Sobolev spaces on the sphere	
		7.4.1 Definition and properties	
		7.4.2 Kernel bounds	
		7.4.3 NTK on the sphere	

1 Introduction

Direct approximation results for a large variety of methods, including neural networks, are typically of the form

$$\inf_{\theta} \|f_{\theta} - f\| \le n(\theta)^{-r}, \quad f \in K.$$
 (1.1)

I.e. a target function f is approximated by an approximation method f_{θ} , parametrized by some degrees of freedom or weights θ up to a rate $n(\theta)^{-r}$ for some $n(\theta)$ that measures the richness of the approximation method as width, depth or number of weights for neural networks. Generally, the approximation rate can be arbitrarily slow unless the target f is contained in some compact set K, which depends on the approximation method and application and is typically a unit ball in a Sobolev, Besov, Barron or other normed smoothness space. Such results are well established for a variety of neural network architectures and compact sets K, however, these results rarely address how to practically compute the infimum in the formula above and instead use hand-picked weights.

On the other hand, the neural network optimization literature, typically considers discrete error norms (or losses)

$$||f_{\theta} - f||_* := \left(\frac{1}{n} \sum_{i=1}^{n} |f_{\theta}(x_i) - f(x_i)|^2\right)^{\frac{1}{2}}$$

together with neural networks that are over-parametrized, i.e. for which the number of weights is larger than the number of samples n so that they can achieve zero training error