

Heintze-Karcher Inequality for Anisotropic Free Boundary Hypersurfaces in Convex Domains

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Abstract. In this paper, we prove an optimal Heintze-Karcher-type inequality for anisotropic free boundary hypersurfaces in general convex domains. The equality is achieved for anisotropic free boundary Wulff shapes in a convex cone. As applications, we prove Alexandrov-type theorems in convex cones.

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1 Introduction

The Heintze-Karcher inequality states that for a bounded domain Ω in $\mathbb{R}^{n+1}$ with smooth and mean convex boundary $\Sigma = \partial\Omega$, it holds that

$$\int_{\Sigma} \frac{1}{H} dA \geq \frac{n+1}{n} |\Omega|, \quad (1.1)$$

and equality in (1.1) holds if and only if Σ is a geodesic sphere. Here H is the mean curvature of Σ and Σ is said to be mean convex if $H > 0$. It was first proved by Heintze-Karcher [8] and in the present form (1.1) by Ros [17]. A combination of the Heintze-Karcher inequality (1.1) and the Minkowski-Hsiung formula yields Alexandrov's theorem for embedded closed constant mean curvature (CMC) hypersurfaces, namely any closed embedded CMC hypersurface is a sphere, first proved by Alexandrov [1] via moving plane method and by Reilly [16] and Ros [17] via integral method. For the history

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of the study of Heintze-Karcher's inequality and Alexandrov's theorem, we refer to [9] and the references therein. An anisotropic version of the Heintze-Karcher inequality has been proved by He-Li-Ma-Ge [7], which leads to an Alexandrov-type theorem for embedded closed constant anisotropic mean curvature hypersurfaces. Heintze-Karcher-type inequalities in space forms and more generally, in warped product manifolds, have been proved by Brendle [2] (see also [12]).

Recently, we have studied the Heintze-Karcher-type inequality for hypersurfaces with boundary in the half-space $\mathbb{R}_+^{n+1} = \{x \in \mathbb{R}^{n+1} | \langle x, E_{n+1} \rangle > 0\}$. Precisely, we prove the following result.

Theorem 1.1 ([9, 10]). *Let $\Sigma \subset \overline{\mathbb{R}_+^{n+1}}$ be an embedded compact C^2 -hypersurface with boundary $\partial\Sigma$ which intersects $\partial\mathbb{R}_+^{n+1}$ transversally such that $\langle v_F(x), -E_{n+1} \rangle \leq 0$ for any $x \in \partial\Sigma$. Let Ω denote the domain enclosed by Σ and $\partial\mathbb{R}_+^{n+1}$. Assume the anisotropic mean curvature H^F of Σ is positive. Then we have*

$$\int_{\Sigma} \frac{F(v)}{H^F} dA \geq \frac{n+1}{n} |\Omega|. \quad (1.2)$$

Moreover, equality in (1.2) holds if and only if Σ is an anisotropic free boundary Wulff cap.

A hypersurface Σ , which intersects $\partial\mathbb{R}_+^{n+1}$ transversally, is called anisotropic free boundary if $\langle v_F(x), -E_{n+1} \rangle = 0$ for any $x \in \partial\Sigma$, where v_F is the anisotropic normal of Σ . A Wulff cap is part of a Wulff shape. Regarding the anisotropy F and anisotropic quantities with a sub- or superscription F , we use the notations in [10]. A brief overview is also provided in Section 2.

Using Theorem 1.1, we have proved an Alexandrov-type theorem for anisotropic free boundary or anisotropic capillary hypersurfaces in $\mathbb{R}_+^{n+1}$. This Alexandrov-type theorem for isotropic capillary hypersurfaces in $\mathbb{R}_+^{n+1}$ was first proved by Wente [21] via moving plane method.

In this paper, we continue the study of Heintze-Karcher-type inequality in a more general setting, in particular, for hypersurfaces with boundary in general convex domains.

Let $\mathcal{K}$ be the class of all convex domains in $\mathbb{R}^{n+1}$. We emphasize that in this paper for each $K \in \mathcal{K}$, ∂K is not assumed to be C^1 , in other words, ∂K may have singularity. In order not to make situations too complicated, we restrict us to consider a subset of $\mathcal{K}$, denoted by $\mathcal{K}_P$, which contains convex domains with milder singularities, which we will describe.

We first define the class of convex polytopes with non-empty interior by $\mathcal{P}$. Each element $P \in \mathcal{P}$ can be expressed

$$P = \bigcap_{j \in J} \{u_j \leq 0\},$$

where J is a finite index set and u_j ($j \in J$) are affine linear functions on $\mathbb{R}^{n+1}$, i.e., P is determined by a family of inequalities $u_j \leq 0$ ($j \in J$). The family is called *irredundant* if $P \neq \bigcap_{j \in J, j \neq l} \{u_j \leq 0\}$ for any $l \in J$. We can and will always assume that P is irredundant. A