

Well-Posedness of a Nonlocal Stage-Structured Population Model with Free Boundary[§]

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Abstract. We propose a delay-induced nonlocal free boundary problem by modeling the invasion of a two-stage structured species, where the nonlocal interaction is caused jointly by time delay, free boundary and the diffusion. After establishing a comparison principle and a priori boundedness estimates, we prove the local and global existence of classical solutions for the model.

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1 Introduction

This paper is concerned with the following nonlocal problem with Stefan type free boundary conditions:

$$\begin{cases} u_t = A(t, x)u_{xx} + B(t, x)u_x + C(t, x, u, v(\tau(t), x; t)), & t > 0, x \in (g(t), h(t)), \\ u(t, g(t)) = 0, g'(t) = -\mu u_x(t, g(t)), & t > 0, \\ u(t, h(t)) = 0, h'(t) = -\mu u_x(t, h(t)), & t > 0, \\ u(\theta, x) = \phi(\theta, x), & \theta \in [-\tau(0), 0], x \in [g(\theta), h(\theta)], \end{cases} \quad (P)$$

where $v(\tau(t), x; t)$ is the solution $v(s, x)$, evaluated at $s = \tau(t)$, of following problem

$$\begin{cases} v_s = E(s, x)v_{xx} + F(s, x)v_x + G(s, x)v, & s \in (0, \tau(t)], x \in (g(s+t-\tau(t)), h(s+t-\tau(t))), \\ v(s, x) = 0, & s \in (0, \tau(t)], x = g(s+t-\tau(t)) \text{ or } h(s+t-\tau(t)), \\ v(0, x) = f(t-\tau(t), u(t-\tau(t), x)), & x \in [g(t-\tau(t)), h(t-\tau(t))]. \end{cases} \quad (Q)$$

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Here $A, B, C, E, F, G, f, \tau$ are given functions that will be specified later.

This model is used to describe the population invasion of an alien species, which is classified by age into mature stage u and immature stage v ; an individual at time t belongs to immature stage if and only if its age does not exceed a time-dependent number $\tau(t)$, where $\tau(t)$ is often called the maturation period. As such, $v(\tau(t), x; t)$ is the newly added mature population at time t , which is an evolution result of newborns $f(t - \tau(t), u(t - \tau(t), x))$ at time $t - \tau(t)$. Here f is the birth function of mature population. In the model, we also assume that the mature population is responsible for the expansion of the habitat $(g(t), h(t))$ by obeying the Stefan type free boundary conditions, while the immature population v moves inside this habitat but does not contribute to the habitat expansion. Thus, the model is highly nonlocal in space and time, involving also the to-be-determined habitat over the time interval $(t - \tau(t), t)$. The derivation details of this model will be presented in the next section.

The model (P)-(Q) is closely related to some classical models in literature. If we choose $\tau(t) \equiv 0$ and

$$A \equiv 1, \quad B \equiv 0, \quad C = -u + v$$

in (P)-(Q), then it becomes the following problem:

$$\begin{cases} u_t = u_{xx} - u + f(u), & t > 0, x \in (g(t), h(t)), \\ u(t, g(t)) = 0, g'(t) = -\mu u_x(t, g(t)), & t > 0, \\ u(t, h(t)) = 0, h'(t) = -\mu u_x(t, h(t)), & t > 0, \\ u(0, x) = \phi(0, x), & x \in [g(0), h(0)], \end{cases} \quad (1.1)$$

which was proposed by Du and Lin [7] in 2010. With a KPP type setting, they revealed a spreading-vanishing dichotomy for the long-term behavior of solutions, which is different from the hair-trigger effect established in the earlier celebrated work [1] by Aronson and Weinberger in 1970's for the Cauchy problem of the KPP equation. We refer to [2] for an interpretation of the Stefan type free boundary conditions in population ecology.

In the past decade, there have been various extensions of the work [7] in several directions. For instance, Du and Lou [9] gave a rather complete description of the long-term behavior of solutions for (1.1) with general nonlinearities. Du, Guo and Peng [6] considered a time periodic case in radially symmetric higher dimension space. Wang [24] extended it to the case where the intrinsic growth rate is sign-changing in time, by a delicate application of principle eigenvalues. Gu, Lin and Lou [12] incorporated advection into the model and found different effects of large and small advection, see also [13, 22]. There also have been an increasing interest in extensions to systems, including competition models and predator-prey models, see for example [3, 8, 10, 14, 17, 26, 27, 29] and references therein.

Based on the framework of [7], Du, Fang and Sun [5] incorporated time delay into the